

B-tree Design Data Structure for Ordered Collection

Memory Type	approximate access time (ns)	cost per megabyte (\$)
cache	5-20	10-75
main memory	60-120	0.50-5.00
secondary storage	20,000,000	.001-0.10

RAM →

hard drive →

Table 29.1 Approximate access times in nanoseconds (ns) as compared with the cost for cache, main memory, and secondary storage (disk).

Designed for situation in which n (# elements or tags in a tagged collection) is so large that B-tree + n references to elements cannot fit in main memory.

24K bytes ↓

Data is moved from disk to RAM in chunk called page

Page Fault

Virtual memory lets you store data in secondary storage (act as if its in main memory)

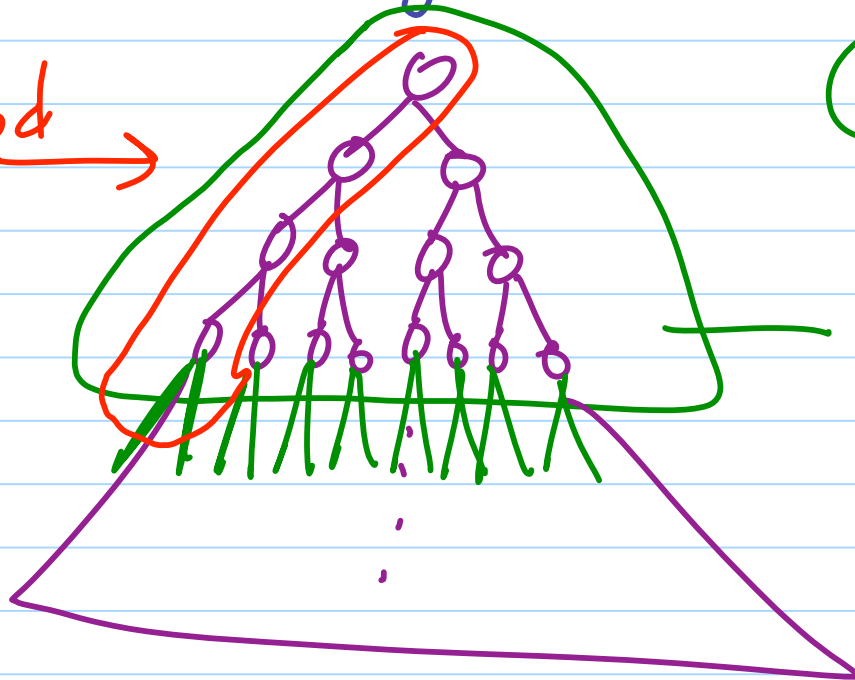
If program accesses data not in main memory, it's a page fault.

For a binary search tree, information we must store.

- per tag
- tag (comparable) date of a historical event
 - location on disk (secondary storage) for the rest of information associated with event
 - parent ref
 - left child ref
 - right child ref

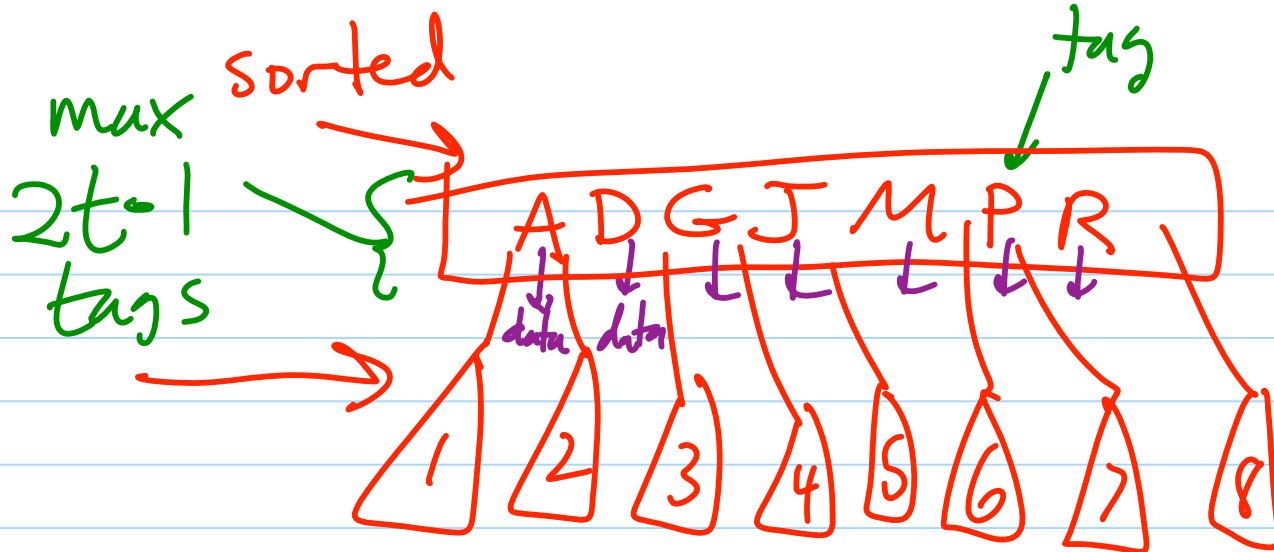
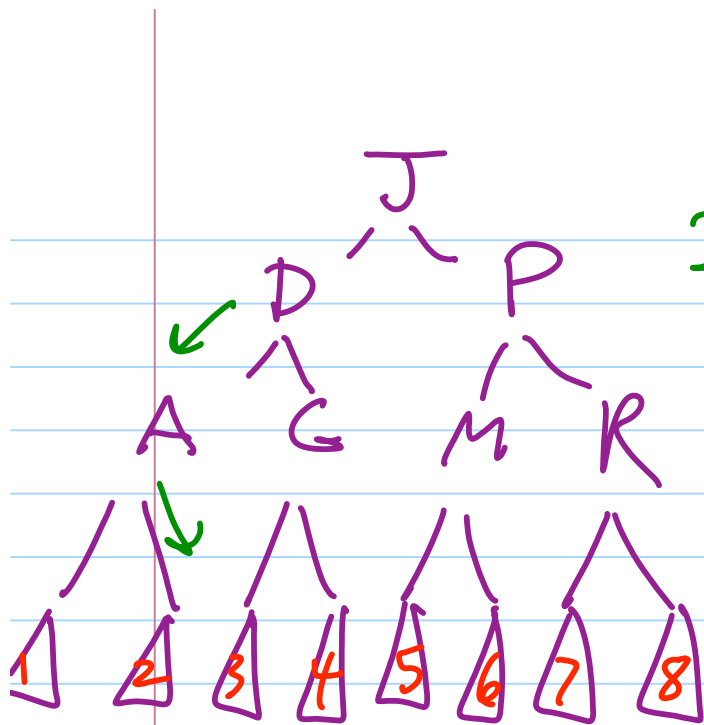
Want to group nodes of binary search tree into a single B-tree node that fills a disk page

not a good choice because we may only look at one node. Usually, look at very few

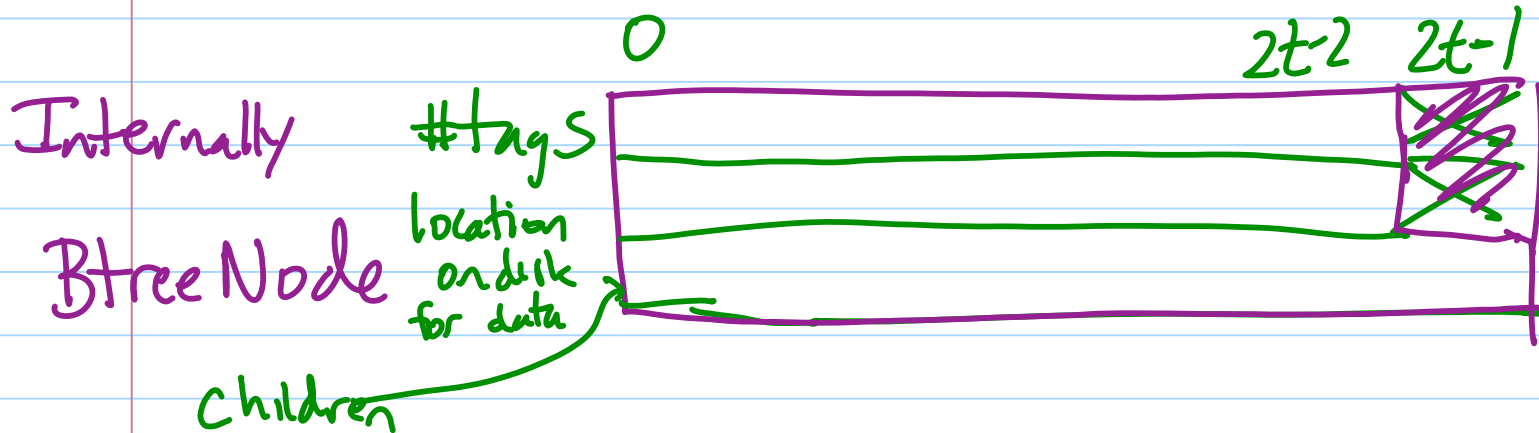


Good

make this a disk page (go as many levels as we can fit)
 $1/16^{\text{th}}$ of data left to consider



INORDER



children
is
at most
2t